

Reg No.: _____

Name: _____

APJ ABDUL KALAM TECHNOLOGICAL UNIVERSITY

Sixth semester B.Tech examinations (S), September 2020

Course Code: AE302**Course Name: PROCESS CONTROL**

Max. Marks: 100

Duration: 3 Hours

PART A*Answer any two full questions, each carries 15 marks.*

Marks

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|---|--|------|
| 1 | a) Explain the characteristics of physical system. | (10) |
| | b) Discuss the incentives for process control. | (5) |
| 2 | a) Define manipulated variable, controlled variable and load variable. | (6) |
| | b) What is the use of scaling in industries? Explain scaling with example. | (9) |
| 3 | a) What is meant by linearizing effect of equal percentage valve? | (5) |
| | b) Analyse liquid level control loop. | (10) |

PART B*Answer any two full questions, each carries 15 marks.*

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|---|--|------|
| 4 | a) What are the elements of feed back control system? | (10) |
| | b) Discuss the goals of controller tuning. | (5) |
| 5 | a) Explain control performance measures for set-point changes. | (7) |
| | b) Describe feed back feed forward controller with suitable example. | (8) |
| 6 | a) Explain cascaded controller with example. | (9) |
| | b) What are the different type of selective control system? | (6) |

PART C*Answer any two full questions, each carries 20 marks.*

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| 7 | a) What is RGA? Mention the importance of RGA for predicting interaction in multivariable control system. | (10) | | | | | |
| | b) Explain the multi-loop control performance through loop pairing. | (10) | | | | | |
| 8 | a) What is self tuning controller? Explain. | (8) | | | | | |
| | b) Draw ANN neuron model and explain elements in the model. | (8) | | | | | |
| | c) Distinguish fuzzy set from crisp set. | (4) | | | | | |
| 9 | a) Explain the multiloop control performance through single loop enhancement. | (8) | | | | | |
| | b) Explain <table border="0" style="margin-left: 20px;"> <tr> <td>i)</td> <td>Smith Predictor</td> <td></td> </tr> <tr> <td>ii)</td> <td>Model Predictive Controller</td> <td>(12)</td> </tr> </table> | i) | Smith Predictor | | ii) | Model Predictive Controller | (12) |
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| ii) | Model Predictive Controller | (12) | | | | | |
